Quick setup guide

Radar sensor for continuous level measurement of liquids and bulk solids

NCR-86

Four-wire 4 ... 20 mA/HART 90 ... 253 V AC; 50/60 Hz





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Information:

This quick setup guide enables quick setup and commissioning of your instrument.

You can find supplementary information in the corresponding, more detailed Operating Instructions Manual as well as the Safety Manual that comes with instruments with SIL qualification. These manuals are available on our homepage.

Operating instructions NCR-86 - Four-wire 4 ... 20 mA/HART 90 ... 253 V AC; 50/60 Hz: Document-ID 1034064

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1 For your safety

1.1 Authorised personnel

All operations described in this documentation must be carried out only by trained and authorized personnel.

During work on and with the device, the required personal protective equipment must always be worn.

1.2 Appropriate use

NCR-86 is a sensor for continuous level measurement.

You can find detailed information about the area of application in chapter "Product description".

Operational reliability is ensured only if the instrument is properly used according to the specifications in this document as well as possible supplementary instructions.

1.3 Warning about incorrect use

Inappropriate or incorrect use of this product can give rise to application-specific hazards, e.g. vessel overfill through incorrect mounting or adjustment. Damage to property and persons or environmental contamination can result. Also, the protective characteristics of the instrument can be impaired.

1.4 General safety instructions

This is a state-of-the-art instrument complying with all prevailing regulations and directives. The instrument must only be operated in a technically flawless and reliable condition. The operating company is responsible for the trouble-free operation of the instrument. When measuring aggressive or corrosive media that can cause a dangerous situation if the instrument malfunctions, the operating company has to implement suitable measures to make sure the instrument is functioning properly.

The safety instructions in this instructions manual, the national installation standards as well as the valid safety regulations and accident prevention rules must be observed.

For safety and warranty reasons, any invasive work on the device beyond that described in this instructions manual may be carried out only by personnel authorised by us. Arbitrary conversions or modifications are explicitly forbidden. For safety reasons, only the accessory specified by us must be used.

To avoid any danger, the safety approval markings and safety tips on the device must also be observed.

The low transmitting power of the radar sensor is far below the internationally approved limits. No health impairments are to be expected with intended use. The band range of the measuring frequency can be found in chapter "*Technical data*".



1.5 Mode of operation - Radar signal

Country or region specific settings for the radar signals are determined via the mode. The operating mode must be set in the operating menu via the respective operating tool at the beginning of the setup.



Caution:

Operating the device without selecting the relevant mode constitutes a violation of the regulations of the radio approvals of the respective country or region.

1.6 Installation and operation in the USA and Canada

This information is only valid for USA and Canada. Hence the following text is only available in the English language.

Installations in the US shall comply with the relevant requirements of the National Electrical Code (NEC - NFPA 70) (USA).

Installations in Canada shall comply with the relevant requirements of the Canadian Electrical Code (CEC Part I) (Canada).

A Class 2 power supply unit has to be used for the installation in the USA and Canada.



2 Product description

2.1 Configuration

Type label

The type label contains the most important data for identification and use of the instrument:

- Instrument type
- Information about approvals
- Configuration information
- Technical data
- Serial number of the instrument
- QR code for device identification
- Numerical code for Bluetooth access (optional)
- Manufacturer information

Documents and software

Further information can be found on our homepage.

There you will find the documentation and further information about the device.

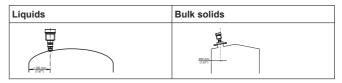


3 Setup - the most important steps

Prepare

| What? | How? |
|-----------------|---|
| Identify sensor | Scan QR code on type label, check sensor data |

Mount and connect sensor

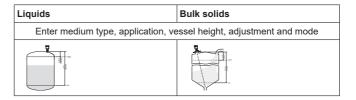


| Connection technology | Wiring plan |
|-----------------------|-------------|
| | 0 = 00.0 |

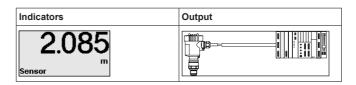
Select adjustment



Parameterize sensor



Check measured value



¹⁾ Download via Apple App Store, Google Play Store, Baidu Store



4 Mounting

4.1 **Mounting instructions**

Polarisation

Radar sensors for level measurement emit electromagnetic waves. The polarisation is the direction of the electrical share of these waves. It is identifiable by a mark on the housing, see the following drawing:

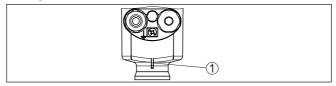


Fig. 1: Position of the polarisation

1 Nose for marking the direction of polarisation

Turning the housing changes the polarisation and thus also the effect of false echoes on the measured value.



Note:

Therefore, pay attention to the position of the polarisation when mounting or when making subsequent changes. Fix the housing to prevent a change in the metrological properties (see chapter "Housing features").

Mounting position liquids

When mounting the device, keep a distance of at least 200 mm (7.874 in) from the vessel wall. If the device is installed in the center of dished or round vessel tops, multiple echoes can arise. However, these can be suppressed by an appropriate adjustment (see chapter "Setup").



Note:



If you cannot maintain this distance, you should carry out a false signal suppression during setup. This applies especially if buildup on the vessel wall is to be expected.2)

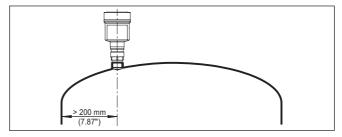


Fig. 2: Mounting of the radar sensor on round vessel tops

²⁾ In this case, it is recommended to repeat the false signal suppression at a later time with existing buildup.



In vessels with conical bottom it can be advantageous to mount the device in the centre of the vessel, as measurement is then possible down to the bottom.

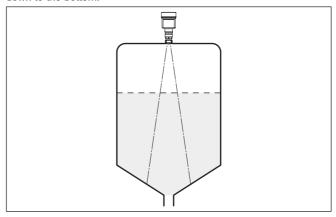


Fig. 3: Mounting of the radar sensor on vessels with conical bottom

Mounting position - bulk solids

Mount the instrument at least 200 mm (7.874 in) away from the vessel wall.

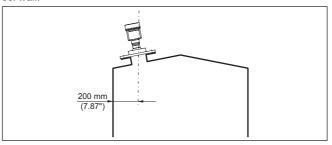


Fig. 4: Mounting the radar sensor on the vessel top

Note:



If you cannot maintain this distance, you should carry out a false signal suppression during setup. This applies especially if buildup on the vessel wall is to be expected.³⁾

³⁾ In this case, it is recommended to repeat the false signal suppression at a later time with existing buildup.



5 Connecting to power supply

5.1 Connecting

Connection technology

The voltage supply and signal output are connected via the springloaded terminals in the housing.

Connection to the display and adjustment module or to the interface adapter is carried out via contact pins in the housing.

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Information:

The terminal block is pluggable and can be removed from the electronics. To do this, lift the terminal block with a small screwdriver and pull it out. When reinserting the terminal block, you should hear it snap in.

Connection procedure

Proceed as follows:

- 1. Unscrew the housing lid
- Loosen compression nut of the cable gland and remove blind plug
- Remove approx. 10 cm (4 in) of the cable mantle (signal output), strip approx. 1 cm (0.4 in) insulation from the ends of the individual wires
- 4. Insert the cable into the sensor through the cable entry



Fig. 5: Connection steps 5 and 6

Insert the wire ends into the terminals according to the wiring plan

Information:



Solid cores as well as flexible cores with wire end sleeves are inserted directly into the terminal openings. In case of flexible cores without end sleeves, press the terminal from above with a small screwdriver, the terminal opening is then free. When the screwdriver is released, the terminal closes again.



- Check the hold of the wires in the terminals by lightly pulling on them
- Connect the cable screening to the internal ground terminal, connect the outer ground terminal to potential equalisation in case of power supply via low voltage
- Connect the lead cable for voltage supply in the same way
 according to the wiring plan, in addition connect the ground
 conductor to the inner ground terminal when powered with mains
 voltage.
- 9. Tighten the compression nut of the cable entry gland. The seal ring must completely encircle the cable
- 10. Screw the housing lid back on

The electrical connection is finished.

Information:

The terminal blocks are pluggable and can be removed from the housing insert. To do this, lift the terminal block with a small screw-driver and pull it out. When inserting the terminal block again, you should hear it snap in.

5.2 Wiring plan, double chamber housing



The following illustrations apply to the non-Ex as well as to the Ex d version.

Electronics compartment

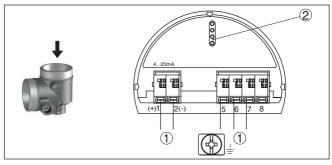


Fig. 6: Electronics compartment - double chamber housing

- 1 Internal connection to the connection compartment
- 2 For display and adjustment module or interface adapter

Information:

Ì T

The connection of an external display and adjustment unit is not possible with the Ex d version.



Connection compartment with mains voltage

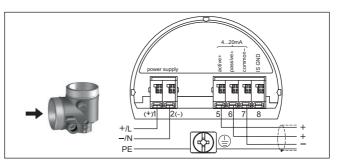


Fig. 7: Connection compartment with double chamber housing with mains voltage

| Terminal | Function | Polarity |
|----------|---|----------|
| 1 | Voltage supply | +/L |
| 2 | Voltage supply | -/N |
| 5 | 4 20 mA output (active) | + |
| 6 | 4 20 mA output (passive) | + |
| 7 | Mass - output | - |
| 8 | Function ground when installing according to CSA (Canadian Standards Association) | |

5.3 Switch-on phase

After connection of the device to power supply, the device first carries out a self-test:

- Internal check of the electronics
- Indication of the status message "F 105 Determine measured value" on the display or PC
- · The output signal jumps briefly to the set fault current

Then the actual measured value is output to the signal cable. The value takes into account settings that have already been carried out, e.g. default setting.



6 Set up with the display and adjustment module

6.1 Insert display and adjustment module

The display and adjustment module can be inserted into the sensor and removed again at any time. You can choose any one of four different positions - each displaced by 90°. It is not necessary to interrupt the power supply.

Proceed as follows:

- 1. Unscrew the housing lid
- 2. Place the display and adjustment module on the electronics in the desired position and turn it to the right until it snaps in.
- 3. Screw housing lid with inspection window tightly back on

Disassembly is carried out in reverse order.

The display and adjustment module is powered by the sensor, an additional connection is not necessary.



Fig. 8: Installing the display and adjustment module in the double chamber housing

Note:

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If you intend to retrofit the instrument with a display and adjustment module for continuous measured value indication, a higher lid with an inspection glass is required.

6.2 Parameterization

6.2.1 Lock/Unlock adjustment

Lock/Unlock adjustment (non-SIL) In this menu item you safeguard the sensor parameters against unauthorized or unintentional modifications.

Information:

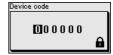


The non-SIL version of the device is delivered without activated access protection. If necessary, the access protection can be activated and the device locked.











When the adjustment is blocked, only the following adjustment functions are possible without entering the device code:

- · Select menu items and show data
- Read data from the sensor into the display and adjustment module



Caution:

When the adjustment is blocked, the adjustment via other systems is also blocked

Releasing the sensor adjustment is also possible in any menu item by entering the device code.

Lock/Unlock adjustment (SIL)

In this menu item you safeguard the sensor parameters against unauthorized or unintentional modifications.



Information:

The SIL version of the device is delivered in locket state.

Safe parameterization:

To avoid possible errors during parameterization in a non-safe user environment, a verification procedure is used that makes it possible to detect parameterization errors reliably. For this, safety-relevant parameters must be verified before they are stored in the device. In normal operating condition, the instrument is also locked against parameter changes through unauthorized access.









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Information:

If the device code has been changed and forgotten, the enclosed information sheet "Access Protection" provides an emergency device code.

Character string comparison and serial number:

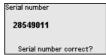
You first have to carry out the character string comparison. This is used to check the character respresentation.



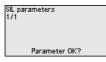
Confirm if the two character strings are identical. The verification texts are provided in German and in the case of all other menu languages, in English.

Afterwards you confirm that the serial number of your instrument was carried over correctly. This is used to check device communication





In the next step, the instrument checks the data of the measurement and decides by means of the evaluation results if a functions test is required. If a function test is necessary, the following message is displayed.





In this case, you have to carry out a function test.

Function test:

During a function test, you have to test the safety function of the instrument in the vessel with the original medium.



You can find the detailed sequence of the function test in chapter "Functional safety (SIL)" of the operating instructions.

Verify parameter:

All safety-relevant parameters must be verified after a change. After the function test, all modified, safety-relevant parameters will be listed. Confirm the modified values one after the other.





If the described process of parameter adjustment was run through completely and correctly, the instrument will be locked and hence ready for operation.



Otherwise the instrument remains in the released and hence unsafe condition.



Note:

When the adjustment is blocked, the adjustment via other systems is also blocked.

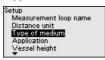


Type of medium

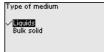
6.2.2 Setup

This menu item allows you to adapt the sensor to the different measuring conditions of the media "Liquid" or "Bulk solid".

The corresponding application is selected in the following menu item "Application".







Vessel height

Through this selection the operating range of the sensor is adapted to the vessel height. Hence the measurement reliability is increased considerably under different basic conditions.







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Note

Regardless of this, the min. adjustment must also be carried out (see following section).

Adjustment

Since the radar sensor is a distance measuring instrument, it is the distance from the sensor to the medium surface that is measured. To indicate the actual level, the measured distance must be assigned to a certain height percentage (min./max. adjustment).

During adjustment, enter the respective measuring distance when the vessel is full and empty (see the following examples):

Liquids:

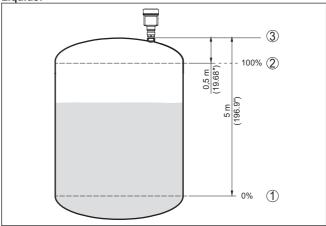


Fig. 9: Parameterisation example min./max. adjustment - liquids

- 1 Min. level = max. meas. distance (distance B)
- 2 Max. level = min. meas. distance (distance A)
- 3 Reference plane





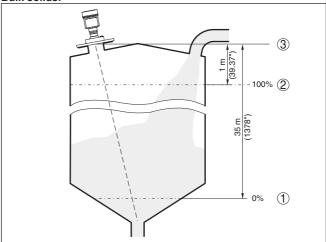


Fig. 10: Parameterisation example min./max. adjustment - bulk solids

- 1 Min. level = max. meas. distance (distance B)
- 2 Max. level = min. meas. distance (distance A)
- 3 Reference plane

If these values are not known, and adjustment can for example be carried out with the distances of 10 % and 90 %.

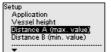
The starting point for these distance specifications is always the reference plane, e.g. the sealing surface of the thread or flange. Information on the reference plane can be found in the chapters "Mounting instructions" resp. "Technical data". The actual filling height is then calculated on the basis of these entries.

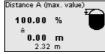
The actual product level during this adjustment is not important, because the min./max. adjustment is always carried out without changing the product level. These settings can be made ahead of time without the instrument having to be installed.

Distance A (max. value)

Proceed as follows:

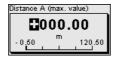
 Select with [->] the menu item Distance A (max. value) and confirm with [OK].





- Edit the distance value with [OK] and set the cursor to the requested position with [->].
- Adjust the requested distance value for 100 % with [+] and store with [OK].



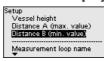


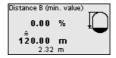
4. Move with [ESC] and [->] to the min. adjustment

Distance B (min. value)

Proceed as follows:

 Select with [->] the menu item "Distance B (min. value)" and confirm with [OK].





- Edit the distance value with [OK] and set the cursor to the requested position with [->].
- Set the requested distance value for 0 % (e.g. distance from the sensor up to the vessel bottom) with [+] and save with [OK]. The cursor now jumps to the distance value.



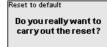
6.2.3 Reset

Reset

During a reset, parameter settings made by the user are reset to the values of the factory settings. You can fined the values in chapter "Menu overview".







•

Information:

The language and Bluetooth access code are not reset, a currently running simulation however is aborted.

Reset - Factory settings:

- Restoring the factory and order-specific parameter settings
- Resetting a user-set measuring range to the recommended measuring range (see chapter "Technical data")
- Deleting a created false signal suppression, a user-programmable linearisation curve as well as the measured value and echo curve memory⁴⁾

Reset - Restart:

Is used to restart the device without switching off the operating voltage.

⁴⁾ The event and parameter change memories are maintained.





Note:

For the duration of the reset, the device changes its behaviour from the normal measuring operation. Therefore, observe the following for downstream systems:

- The current output outputs the set false signal
- The Asset-Management function outputs the message "Maintenance" aus

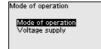
6.2.4 Extended settings

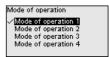
This menu item contains operational settings of the sensor.

Mode:

Country or region-specific settings for the radar signals are determined via the operating mode.







- Mode 1: EU, Albania, Andorra, Azerbaijan, Australia, Belarus, Bosnia and Herzegovina, Canada, Liechtenstein, Moldavia, Monaco, Montenegro, New Zealand, Northern Macedonia, Norway, San Marino, Saudi Arabia, Serbia, Switzerland, Turkey, Ukraine, United Kingdom, USA
- Mode of operation 2: Brazil, Japan, South Korea, Taiwan, Thailand
- Mode of operation 3: India, Malaysia, South Africa
- Mode of operation 4: Russia, Kazakhstan

Note:

1

Depending on the operating mode, metrological properties of the device can change (see chapter "*Technical data, input variable*").

Voltage supply:

The power supply determines whether the sensor is in operation permanently or only in accordance with certain requirements.





Mode



7 Set up with Smartphone/tablet

7.1 Preparations

System requirements

Make sure that your smartphone/tablet meets the following system requirements:

- Operating system: iOS 8 or newer
- · Operating system: Android 5.1 or newer
- Bluetooth 4.0 LE or newer

Download the adjustment app from the "Apple App Store", "Google Play Store" or "Baidu Store" to your smartphone or tablet.

Make sure that the Bluetooth function of the display and adjustment module is activated. For this, the switch on the bottom side must be set to "On".

Factory setting is "On".

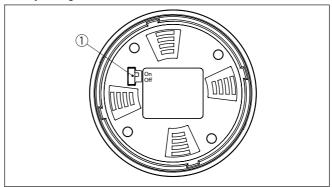


Fig. 11: Activate Bluetooth

1 Switch

On = Bluetooth active

Off = Bluetooth not active

7.2 Connecting

Connecting

Start the adjustment app and select the function "Setup". The smartphone/tablet searches automatically for Bluetooth-capable instruments in the area

The message "Connecting ..." is displayed.

The devices found are listed and the search is automatically continued.

Select the requested instrument in the device list.

Authenticate

When establishing the connection for the first time, the operating tool and the sensor must authenticate each other. After the first correct authentication, each subsequent connection is made without a new authentication query.



Enter Bluetooth access code

For authentication, enter the 6-digit Bluetooth access code in the next menu window. You can find the code on the information sheet "Pins and Codes" in the device packaging.

For the very first connection, the adjustment unit and the sensor must authenticate each other.

Bluetooth access code OK

Enter the 6 digit Bluetooth access code of your Bluetooth instrument.

Fig. 12: Enter Bluetooth access code



Note:

If an incorrect code is entered, the code can only be entered again after a delay time. This time gets longer after each incorrect entry.

The message "Waiting for authentication" is displayed on the smartphone/tablet.

Connected

After connection, the sensor adjustment menu is displayed on the respective adjustment tool.

If the Bluetooth connection is interrupted, e.g. due to a too large distance between the two devices, this is displayed on the adjustment tool. The message disappears when the connection is restored.

Change device code

Parameter adjustment of the device is only possible if the parameter protection is deactivated or the adjustment released. When delivered, parameter protection is deactivated by default and can be activated at any time.

It is recommended to enter a personal 6-digit device code. To do this, go to menu "Extended functions", "Access protection", menu item "Protection of the parameter adjustment".

7.3 Parameter adjustment

Enter parameters

The sensor adjustment menu is divided into two areas, which are arranged next to each other or one below the other, depending on the adjustment tool.

- · Navigation section
- Menu item display

The selected menu item can be recognized by the colour change.

Enter the requested parameters and confirm via the keyboard or the editing field. The settings are then active in the sensor.

Close the app to terminate connection.



8 Menu overview

8.1 Display and adjustment module

Setup

| Menu item | Parameter | Selection | Default setting |
|-------------------------------|--------------------------|--|--|
| Measurement loop name | | | Sensor |
| Distance unit | Distance unit | mm, m, in, ft | m |
| Type of medium | Type of medium | Liquid | Liquid ⁵⁾ |
| | | Bulk solid | Bulk solid ⁶⁾ |
| Application | Application - liquid | Storage tank, agitator tank, dosing tank, standpipe, tank/collection basin, plastic tank (measurement through tank top), mobile plastic tank (IBC), level measurement in waters, flow measurement flume/over-flow, pump station/pump shaft, combined sewer overflow, demonstration | Storage tank ⁷⁾ |
| | Application - bulk solid | Silo, bunker, crusher, heap, demonstration | Silo ⁸⁾ |
| Vessel height | | | Recommended meas. range, see chapter "Technical data" |
| Distance A (max. value) | Max. value | | Max. adjustment 100 % corresponds to 0,000 m |
| Distance B (min. value value) | | | Min. adjustment 0 % corresponds to 120,000 m |

Extended settings

| Menu item | Parameter | Selection | Default setting |
|------------------|------------------|-----------|-----------------|
| Temperature unit | | °C, °F, K | °C |
| Damping | Integration time | 0 999 s | 0 s |

⁵⁾ Plastic horn antenna, thread with integrated antenna system, flange with encapsulated antenna system

⁶⁾ Flange with lens antenna

Plastic horn antenna, thread with integrated antenna system, flange with encapsulated antenna system

⁸⁾ Flange with lens antenna



| Menu item | Parameter | Selection | Default setting | |
|-------------------------------|---------------------------------------|--|---|--|
| Current output | Output value | Percent, linearized percent, filling height, distance, scaled, measurement reliability, electronics temperature, measuring rate, operating voltage | Percent | |
| | Output character- | 0 100 % correspond to 4 20 mA | 0 100 % corre- | |
| | istics | 0 100 % correspond to 20 4 mA | spond to 4 20 mA | |
| | Current range | 4 20 mA | 4 20 mA | |
| | | 3.8 20.5 mA | | |
| | Reaction when mal- functions occur | ≤ 3.6 mA, ≥ 21 mA, last valid measured value | ≤ 3.6 mA | |
| Linearisation | Linearization type - liquid | Linear, cylindrical tank, spherical tank, Venturi, trapezoidal weir, rectangular weir, Palmer-Bowlus flume, V-Notch, triangular overfall | Linear | |
| | Linearization type - bulk solids | Linear, conical bottom, pyramid bottom, sloping bottom | Linear | |
| | Intermediate height "h" | | | |
| Scaling | Scaling size | Scaling size (dimensionless, mass, volume, height, pressure, flow, others) | Dimensionless | |
| | | Scaling unit (unit selection depending on scaling size, user-defined) | - | |
| | Scaling format | #, #.#, #.##, #.### | # | |
| | Scaling | Scaling | 100 % correspond to | |
| | | | 0 % correspond to | |
| Indication | Menu language | German, English, French, Spanish, Portuguese, Italian, Dutch, Russian, Chinese, Japanese, Turkish, Polish, Czech | Language is set with the first operation. | |
| | Presentation | One measured value, measured value and bargraph, two measured values | One measured value | |
| | Displayed values 1, 2 | Percent, linearized percent, filling height, distance, scaled, measurement reliability, electronics temperature, current output, current output 2 | Percent | |
| | Backlight | On, Off | On | |
| False signal sup- pression | False signal sup- pression | Create new, expand, delete all | - | |
| Date/Time | Date/Time | Date | Actual date | |
| | | Format: 24 h, 12 h | 24 h | |
| | | Time | Actual time | |
| HART mode | HART address | 0 63 | 0 | |
| | Output mode | Analogue current output with HART, fix current (4 mA) with HART | Analogue current output with HART | |



| Menu item | Parameter | Selection | Default setting | |
|--|----------------|--|-------------------|--|
| Mode | Mode | Mode 1: EU, Albania, Andorra, Azerbaijan, Australia, Belarus, Bosnia and Herzego- vina, Canada, Liechtenstein, Morocco, Moldavia, Monaco, Montenegro, New Zea- land, Northern Macedonia, Norway, San Marino, Saudi Arabia, Serbia, Switzerland, Turkey, Ukraine, United Kingdom, USA | Mode 1 | |
| | | Mode of operation 2: Brazil, Japan, South Korea, Taiwan, Thailand | | |
| | Voltage supply | Mode of operation 3: India, Malaysia, South Africa | Permanent voltage | |
| | | Mode 4: Russia | | |
| | | Permanent voltage supply | | |
| | | Not permanent voltage supply | supply | |
| Copy instrument set- tings | | Read from sensor, store in sensor | - | |
| Special parameters See separate menu overview at the end oc the chapter "Menu overview" of the ing instructions. | | | | |

Reset

| Menu item Parameter | | Selection | Default setting | |
|---------------------|-------|------------------------------------|-----------------|--|
| Reset | Reset | Reset to factory settings, Restart | - | |



9 Supplement

9.1 Technical data

Note for approved instruments

The technical data in the respective safety instructions which are included in delivery are valid for approved instruments (e.g. with Ex approval). These data can differ from the data listed herein, for example regarding the process conditions or the voltage supply.

All approval documents can be downloaded from our homepage.

Electromechanical data

Options of the cable entry

- Cable entry M20 x 1.5; ½ NPT

- Cable gland M20 x 1.5; ½ NPT (cable ø see below table)

- Blind plug M20 x 1.5; ½ NPT

- Closing cap ½ NPT

| Material ca- | Material seal insert | Cable diameter | | | | |
|--------------------------|----------------------|----------------|----------|----------|---------|----------|
| ble gland | | 4.5 8.5 mm | 5 9 mm | 6 12 mm | 7 12 mm | 10 14 mm |
| PA | NBR | - | √ | √ | - | √ |
| Brass, nickel- plated | NBR | V | V | V | - | - |
| Stainless steel | NBR | - | √ | √ | - | √ |

Wire cross-section (spring-loaded terminals)

Massive wire, stranded wire
 Stranded wire with end sleeve
 1.2 ... 2.5 mm² (AWG 24 ... 14)
 Stranded wire with end sleeve
 1.5 mm² (AWG 24 ... 16)

Voltage supply

Operating voltage 90 ... 253 V AC, 50/60 Hz

Reverse voltage protection Integrated

Load resistor (4 ... 20 mA/HART - passive)

- Calculation $(U_{R} - U_{min})/0.022 A$

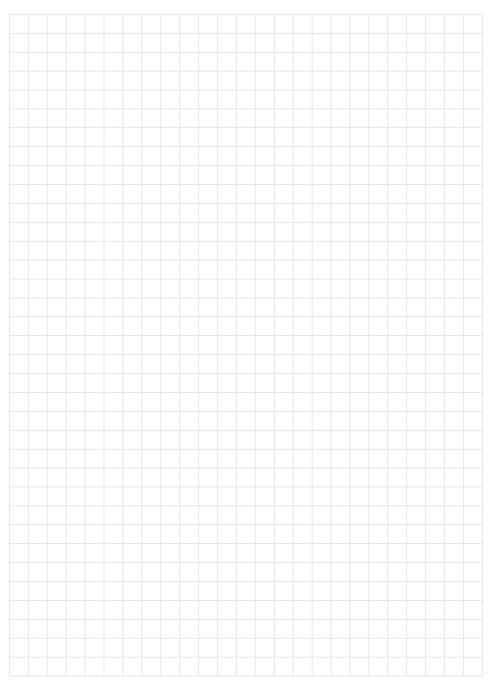
- Example - U_0 = 24 V DC (24 V - 12 V)/0.022 A = 545 Ω

Load resistor (4 ... 20 mA/HART - ac- $< 500 \Omega$

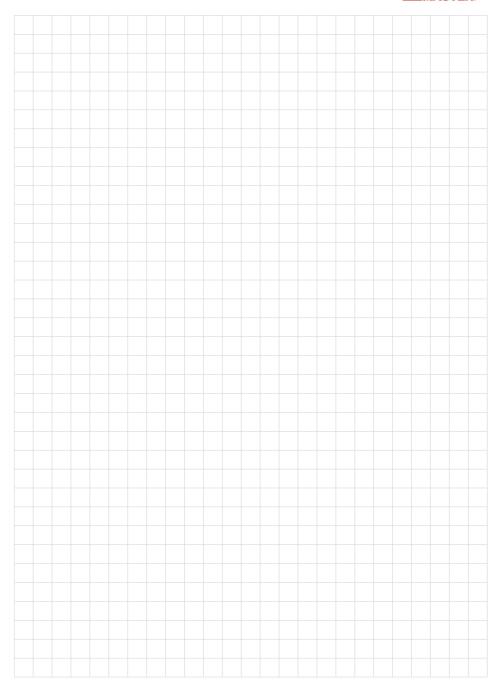
tive)

Max. power consumption 4 VA; 2.1 W

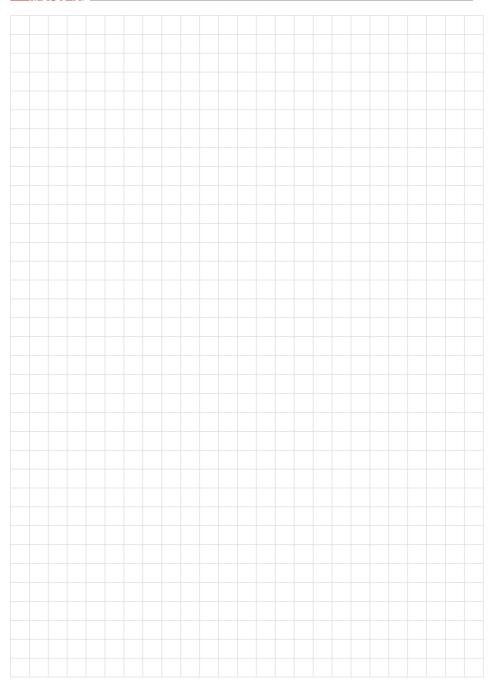












Printing date:



All statements concerning scope of delivery, application, practical use and operating conditions of the sensors and processing systems correspond to the information available at the time of printing.

Subject to change without prior notice

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